

SUBSAMPLING FOR NON-STATIONARY PROCESSES

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I- Almost periodically correlated (APC) processes

I-1 - Examples

▷ $X(t) = X_1(t) \cos t + X_2(t) \cos(\pi t)$, $t \in \mathbb{R}$ where
 $\{X_i(t) : t \in \mathbb{R}\}$, $i = 1, 2$ uncorrelated and stationary processes.

▷ $X(t) = \sum_{m=1}^M A_m X_m(t - d_m) + N(t)$, $t \in \mathbb{R}$ where

- M : number of users;
- A_m and d_m : real parameters (amplitude and time-delay);
- X_m : real-valued, zero-mean, APC,
uncorrelated on one another and on $N := \{N(t) : t \in \mathbb{R}\}$;
- noise N : real-valued, zero-mean and APC.

▷ $X(t) = Z(t) \cos t$ and $Y(t) = Z(t) \cos t + Z(t - 1) \cos(\pi t)$
where Z is an Ornstein Uhlenbeck process.

I-2 - Background

▷ *Definition* . $\{X(t) : t \in \mathbb{R}\}$ **almost periodically correlated** (APC) (Gladyshev, 1963) :

- $E\{X(t)\} = 0$, $X(t) \in \mathbb{R}$,
- $B(t, \tau) = E\{X(t + \tau)X(t)\}$ almost periodic in t for any $\tau \in \mathbb{R}$.

▷ Then (Hurd, 1991)

$$B(t, \tau) \sim \sum_{\lambda \in \Lambda} a(\lambda, \tau) e^{i\lambda t}$$

where the **spectral covariance** is

$$a(\lambda, \tau) = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T B(t, \tau) e^{-i\lambda t} dt,$$

and the **set of frequencies** $\Lambda = \{\lambda \in \mathbb{R} : a(\lambda, \tau) \neq 0\}$ is countable.

Example 1

▷ $X(t) = X_1(t) \cos t + X_2(t) \cos(\pi t)$, $t \in \mathbb{R}$, where
 $\{X_i(t) : t \in \mathbb{R}\}$, $i = 1, 2$, independent, zero-mean and stationary with continuous covariance function $r_i(\cdot)$.

▷ Then, X is an APC process, and

$$\Lambda = \{-2\pi, -2, 0, 2, 2\pi\}$$

$$a(0, \tau) = \frac{1}{2} r_1(\tau) \cos \tau + \frac{1}{2} r_2(\tau) \cos(\pi\tau)$$

$$a(2, \tau) = \overline{a(-2, \tau)} = \frac{1}{4} r_1(\tau) e^{i\tau}$$

$$a(2\pi, \tau) = \overline{a(-2\pi, \tau)} = \frac{1}{4} r_2(\tau) e^{i\pi\tau}.$$

Example 2 (Gardner, 1991)(Gardner, Napolitano, 2006)

$$\triangleright X(t) = \sum_{m=1}^M A_m e^{i\phi_m} X_m(t - d_m) + N(t), \quad \text{where}$$

- user signals $X_m := \{X_m(t) : t \in \mathbb{R}\}$: real-valued, zero-mean, APC, uncorrelated on one another, and on $N := \{N(t) : t \in \mathbb{R}\}$;
- the noise N is also real-valued zero-mean UAPC.

\triangleright Then X is an APC process, and

$$a(\lambda, \tau) = \sum_{m=1}^M A_m^2 e^{-i2\lambda d_m} a_m(\lambda, \tau) + a_N(\lambda, \tau).$$

Example 3

$$\triangleright X(t) = Z(t) \cos t, \quad t \in \mathbb{R},$$

where Z is an Ornstein Uhlenbeck process.

\triangleright Then

$$\begin{aligned} \mathbb{E}\{X(s)X(s + \tau)\} &= e^{-|\tau|} \cos s \cos(s + \tau) \\ &= a(-2, \tau) e^{-i2s} + a(0, \tau) + a(2, \tau) e^{i2s}, \end{aligned}$$

and

$$\begin{aligned} \Lambda &= \{-2, 0, 2\}, \\ a(0, \tau) &= \frac{1}{2} e^{-|\tau|} \cos \tau, \quad a(2, \tau) = \overline{a(-2, \tau)} = \frac{1}{4} e^{-|\tau|} e^{i\tau}. \end{aligned}$$

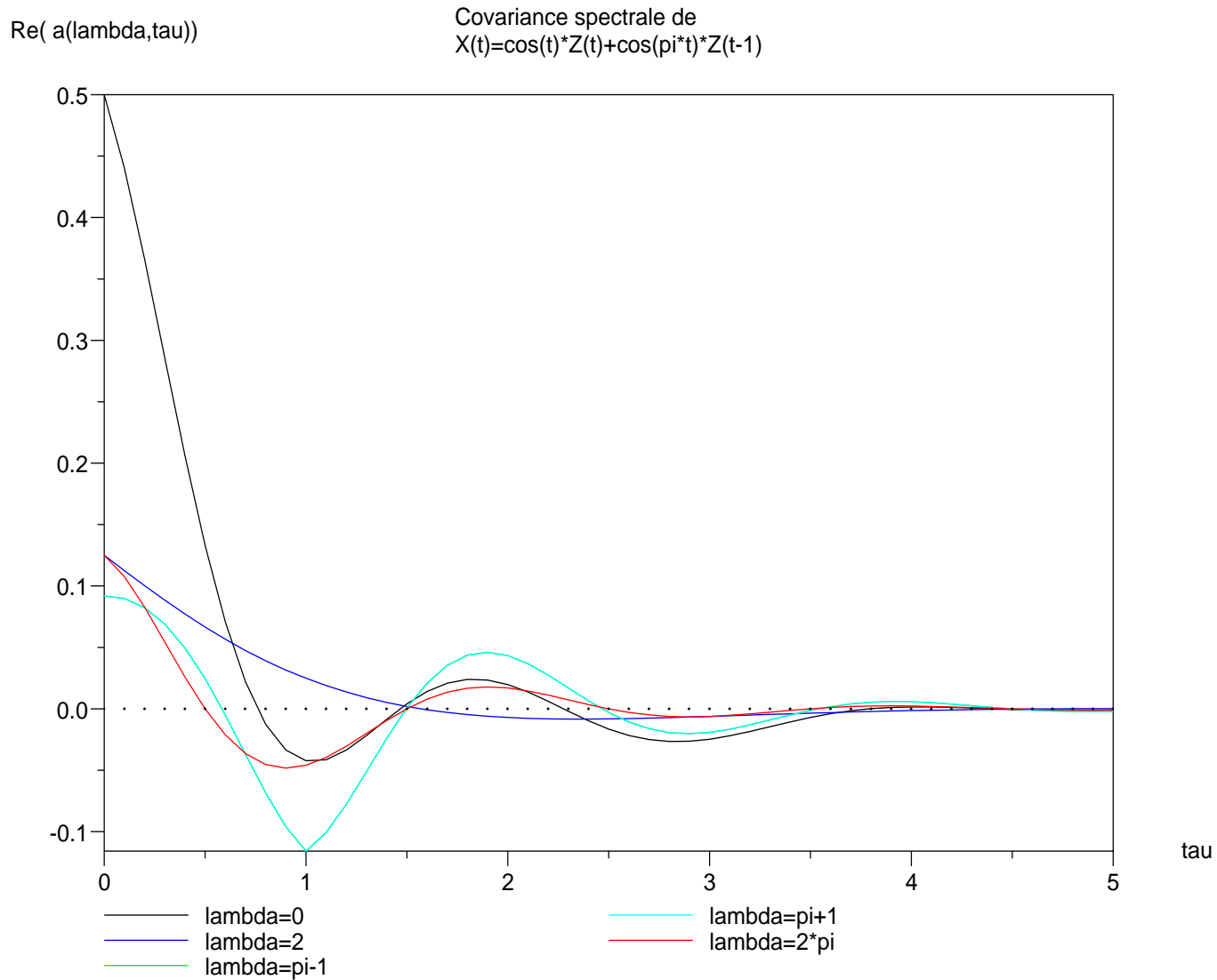
X is APC. More precisely it is *periodically correlated* (PC) :
the function $s \mapsto \mathbb{E}\{X(s)X(s + \tau)\}$ is periodic for any $\tau \in \mathbb{R}$.

Example 4

▷ $Y(t) = Z(t) \cos t + Z(t - 1) \cos(\pi t), \forall t \in \mathbb{R}.$

▷ Then the process Y is APC with

$$\Lambda = \{-2\pi, -1 - \pi, 1 - \pi, -2, 0, 2, \pi - 1, \pi + 1, 2\pi\}.$$



Real parts of the spectral covariances
for $X(t) = Z(t) \cos t + Z(t - 1) \cos(\pi t)$.

I-3 - Continuous time estimation of $a(\lambda, \tau)$

- ▷ *Aim* : estimation of $a(\lambda, \tau)$, and find $\Lambda = \{\lambda \in \mathbb{R} : a(\lambda, \tau) \neq 0\}$.
- ▷ *Observation* : sample $\{X(t); t \in [0, T]\}$ with $T \longrightarrow \infty$.
- ▷ *Estimator of $a(\lambda, \tau)$* (Hurd Leskow, 1992) :

$$\hat{a}_T(\lambda, \tau) = \begin{cases} \frac{1}{T} \int_{|\tau|}^{T-|\tau|} X(t + \tau) X(t) e^{-i\lambda t} dt, & -T/2 \leq \tau \leq T/2, \\ 0, & \text{otherwise.} \end{cases}$$

▷ $\hat{a}_T(\lambda, \tau)$ is a consistent estimator of $a(\lambda, \tau)$:

If $\sup_t \mathbb{E}\{|X(t)|^{4+\delta}\} < \infty$, for $\delta > 0$, and $\alpha_X(t) \longrightarrow 0$ as $t \rightarrow \infty$,

then $\hat{a}_T(\lambda, \tau) \xrightarrow{L^2} a(\lambda, \tau)$.

▷ $\hat{a}_T(\lambda, \tau)$ is asymptotically normal :

If $\sup_t \mathbb{E}\{|X(t)|^{4+\delta}\} < \infty$, $\int_0^T \alpha_X(u)^{\delta/(4+\delta)} du < \infty$, for $\delta > 0$,

$\sum_{\lambda \in \Lambda} 1/\lambda^2 < \infty$, and for any u ,

$v \mapsto \text{cov}\{X(u+v+\tau)X(u+v), X(v+\tau)X(v)\}$ is almost periodic,

then $\sqrt{T}\{\hat{a}_T(\lambda, \tau) - a(\lambda, \tau)\} \xrightarrow{\mathcal{L}} \mathcal{N}(0, V_\infty(\lambda, \tau))$.

In particular

$$T\text{var}\{Re(\widehat{a}(\lambda, \tau))\} \longrightarrow V_\infty^{(1,1)}(\lambda, \tau),$$

with

$$\begin{aligned} V_\infty^{(1,1)}(\lambda, \tau) := & \frac{1}{2} \int_{\mathbb{R}} \left\{ \left(B_c(2\lambda, u + \tau, \tau, u) + B_c(0, u + \tau, \tau, u) \right) \cos(\lambda u) + \right. \\ & \left. + B_s(2\lambda, u + \tau, \tau, u) \sin(\lambda u) \right\} du, \end{aligned}$$

$$B_c(\lambda, u, v, w) := \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \text{cov}\{X(s)X(s+u), X(s+v)X(s+w)\} \cos(\lambda s) ds,$$

$$B_s(\lambda, u, v, w) := \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T \text{cov}\{X(s)X(s+u), X(s+v)X(s+w)\} \sin(\lambda s) ds.$$

▷ The asymptotic covariance of the statistic $\sqrt{T}\{\hat{a}_T(\lambda, \tau) - a(\lambda, \tau)\}$ is quite difficult to handle. For this purpose we will consider the subsampling version of the estimator $\hat{a}_T(\lambda, \tau)$.

▷ We finish this section by providing the definition of α -mixing process, quite useful in subsequent considerations.

Definition . The process X is called α -mixing if $\alpha_X(s) \rightarrow 0$ as $s \rightarrow \infty$, where

$$\alpha_X(s) = \sup \left\{ |P(A \cap B) - P(A)P(B)| : t \in \mathbb{R}, A \in \mathcal{F}_{-\infty}^t(X), B \in \mathcal{F}_{t+s}^\infty(X) \right\}$$

$$\text{and } \mathcal{F}_{t_1}^{t_2}(X) = \sigma \left\{ X(t) ; t_1 \leq t \leq t_2 \right\}.$$

II- Subsampling estimators for stochastic processes

II-1 - Subsampling method (Politis, Romano and Wolf, 1999)

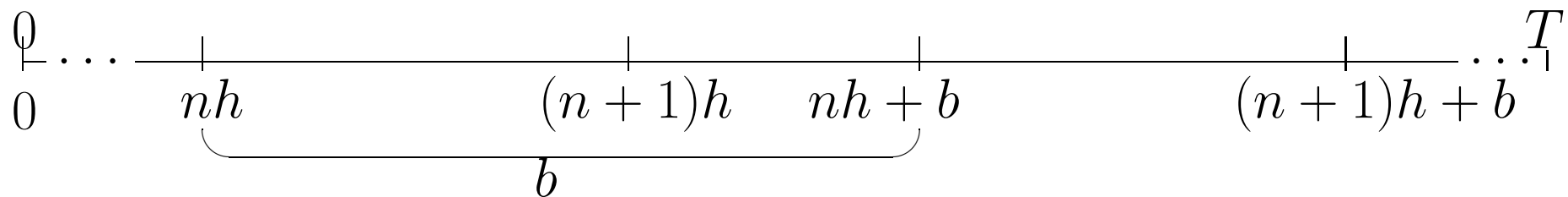
▷ for $h > 0$, $b > 0$ and $n \geq 0$, let $Y_{b,n} := \{X(u) : u \in [nh; nh + b]\}$.

▷ b is the *subsampling size*. $b = b_T \rightarrow \infty$ as $T \rightarrow \infty$, $0 < b \leq T$.

▷ h is the *overlap factor*.

▷ minimal overlap when $h = b$.

▷ maximal overlap when $h \rightarrow 0$.



Definition . The **subsampling version** $\tilde{a}_{b,n}$ of the estimator $\hat{a}_T(\lambda, \tau)$ generated by the data $Y_{b,t}$ is defined as

$$\begin{aligned} \tilde{a}_{b,n} &:= \tilde{a}_{b,n}(\lambda, \tau) = \hat{a}_b(Y_{b,n}) = \hat{a}_b\{X(nh + u) : 0 \leq u \leq b\} \\ &= \begin{cases} \frac{1}{b} \int_{|\tau|}^{b-|\tau|} X(nh + u + \tau) X(nh + u) e^{-i\lambda u} du, & \text{for } |\tau| \leq b/2 \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

Proposition . $\lim_{b \rightarrow \infty} E\{\tilde{a}_{b,n}\} = a(\lambda, \tau) e^{i\lambda nh}$.

Definition . **modified subsampling version** of the estimator $\hat{a}_T(\lambda, \tau)$:

$$\begin{aligned} \hat{a}_{b,n} &:= \tilde{a}_{b,n} e^{-i\lambda nh} \\ &= \begin{cases} \frac{1}{b} \int_{nh+|\tau|}^{nh+b-|\tau|} X(u + \tau) X(u) e^{-i\lambda u} du, & \text{for } |\tau| \leq b/2 \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

II-2 - Empirical process

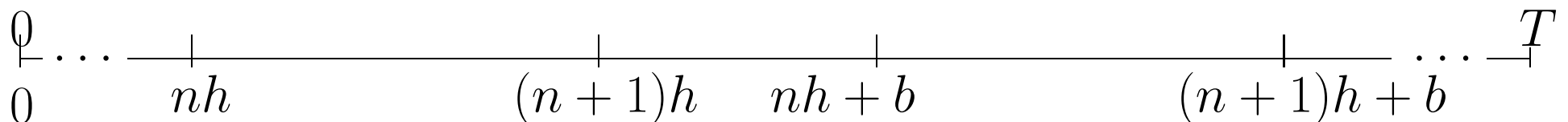
▷ $a(\lambda, \tau)$ and \hat{a}_n and $\hat{a}_{b,n}$ are complex-valued, so we can see them as two-dimensional real-valued : real part and imaginary part.

▷ Partial order in $\mathbb{C} \sim \mathbb{R}^2$ defined by : $x \preceq y \Leftrightarrow x_1 \leq y_1$ and $x_2 \leq y_2$, for $x = x_1 + ix_2$ and $y = y_1 + iy_2$.

Definition . The **empirical process** $L_{T,b}(x)$ induced by the sub-sampling procedure and the sample $\{X(t) : t \in [0, T]\}$ is defined as

$$L_{T,b}(x) = \frac{1}{q} \sum_{n=0}^{q-1} \mathbf{1}\{\sqrt{b}\{\hat{a}_{b,n} - \hat{a}_T\} \preceq x\},$$

where $q = \lfloor \frac{T-b}{h} \rfloor + 1$ is the number of $[nh, nh + b]$ in $[0, T]$.



II-3 - Subsampling consistency

Assume that

$$\triangleright \sup_t \mathbb{E}\{|X(t)|^{4+\delta}\} < \infty, \quad \int_0^T \alpha_X(u)^{\delta/(4+\delta)} du < \infty, \quad \text{for } \delta > 0,$$

$$\triangleright \sum_{\lambda \in \Lambda} 1/\lambda^2 < \infty,$$

$\triangleright v \mapsto \text{cov}\{X(u+v+\tau)X(u+v), X(v+\tau)X(v)\}$ is almost periodic,

$\triangleright b/T \rightarrow 0$, h constant or $h \uparrow$, with $h/T \rightarrow a$, $0 \leq a \leq 1$, as $T \rightarrow \infty$.

\triangleright Then $\hat{a}_T(\lambda, \tau)$ is asymptotically normal.

Denote the limit distribution by $J := \mathcal{N}(0, V_\infty)$.

Lemma . $\sqrt{T}\{\hat{a}_T - a(\lambda, \tau)\} \xrightarrow{\mathcal{L}} J$ and $\sqrt{b}\{\hat{a}_{b,n} - a(\lambda, \tau)\} \xrightarrow{\mathcal{L}} J$,
as $T \rightarrow \infty$ and $n \rightarrow \infty$.

Proof . Bias, variance, APC property, central limit theorem for strong mixing non-stationary processes.

Let $U_{T,b}(x) := \frac{1}{q} \sum_{n=0}^{q-1} \mathbf{1}\{\sqrt{b}\{\hat{a}_{b,n} - a(\lambda, \tau)\} \preceq x\}$.

Lemma . $U_{T,b}(x) \xrightarrow{L^2} J(x)$ at each continuity point of $J(x)$ as $T \rightarrow \infty$.

Proof . Bias, variance, strong mixing inequality for bounded functions.

Theorem

▷ The subsampling is consistent, that is

$$L_{T,b}(x) := \frac{1}{q} \sum_{n=0}^{q-1} \mathbf{1}\{\sqrt{b}\{\hat{a}_{b,n} - \hat{a}_T\} \preceq x\} \xrightarrow{\text{Prob}} J(x)$$

at each point of continuity $x \in \mathbb{R}^2$ of $J(x)$ as $T \rightarrow \infty$.

Theorem

$$\triangleright L_{T,b}^*(x) := \frac{1}{q} \sum_{n=0}^{q-1} \mathbf{1}\{\sqrt{b}\{|\hat{a}_{b,n}|^2 - |\hat{a}_T|^2\} \leq x\} \xrightarrow{\text{Prob}} F(x)$$

at each point of continuity $x \in \mathbb{R}$ of $F(x)$ as $n \rightarrow \infty$, where

$$\sqrt{T}\{|\hat{a}_T|^2 - |a(\lambda, \tau)|^2\} \xrightarrow{\mathcal{L}} F \text{ as } T \rightarrow \infty. \text{ That is}$$

$$F = \mathcal{N}(0, \sigma^2), \text{ where } \sigma^2 = DV_\infty D^\top, \quad D = 2\left(\text{Re}(a(\lambda, \tau)), \text{Im}(a(\lambda, \tau))\right).$$

$$\triangleright \text{For any } \epsilon > 0, \quad \sup_{|x| \geq \epsilon} |L_{T,b}^*(x) - F(x)| \xrightarrow{\text{Prob}} 0.$$

Recall that

$$V_\infty^{(1,1)} := \frac{1}{2} \int_{\mathbb{R}} \left\{ \left(B_c(2\lambda, u + \tau, \tau, u) + B_c(0, u + \tau, \tau, u) \right) \cos(\lambda u) + B_s(2\lambda, u + \tau, \tau, u) \sin(\lambda u) \right\} du,$$

II-5 - Confidence interval

▷ *Corollary* The one-sided subsampling confidence interval for $|a(\lambda, \tau)|^2$ is consistent for any $\alpha \in [0, 1]$

$$P \left[\sqrt{T} \{ |\hat{a}_T|^2 - |a(\lambda, \tau)|^2 \} \leq c_{T,b}(1 - \alpha) \right] \longrightarrow 1 - \alpha, \quad \text{as } T \rightarrow \infty,$$

where $c_{T,b}(1 - \alpha) := \inf \{ x : L_{T,b}^*(x) \geq 1 - \alpha \}$, $\alpha \in [0, 1)$.

▷ *Testing problem* :

$$\begin{cases} H_0 : a(\lambda, \tau) = 0 \\ H_1 : a(\lambda, \tau) \neq 0 \end{cases}$$

II-5 - Choice of b , open problem

▷ b small $\longrightarrow \hat{a}_{b,n}$ is a poor estimator

▷ $b \sim T$ small $\longrightarrow \hat{a}_{b,n} \sim \hat{a}_T$

▷ First approach : "under good hypotheses"

$$\mathbb{E} \left\{ \frac{b}{q} \sum_{n=0}^{q-1} \left(\operatorname{Re}(\hat{a}_{b,n}) - \operatorname{Re}(\hat{a}_T) \right)^2 \right\} - V_{\infty}^{(1,1)} = O\left(\frac{1}{b}\right) + O\left(\frac{b}{T}\right)$$

as $T, b \rightarrow \infty, b < T$.

Take $b \sim \sqrt{T}$. Is it the good choice ?

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