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## Smooth interacting Monte Carlo approximation of contrast functions in HMM

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## Plan

- contrast functions in HMM
- interacting particle approximation
- global interacting particle approximation
- smooth interacting particle approximation
- linear tangent filter
- linear tangent filter : interacting particle approximation
- conclusion

statistical model, depending on a parameter

- Markov chain  $\{X_k, k \geq 0\}$  on  $E$ , with Markov transition kernels

$$\mathbb{P}[X_k \in dx' \mid X_{k-1} = x] = Q_k(x, dx')$$

and initial probability distribution

$$\mathbb{P}[X_0 \in dx] = \mu_0(dx)$$

- observations  $\{Y_k, k \geq 0\}$  with values in  $F$ ,  
satisfying the memoryless channel assumption, with

$$\mathbb{P}[Y_k \in dy' \mid X_k = x'] = g_k(x', y') \lambda_k(dy')$$

and likelihood function

$$\Psi_k(x') = g_k(x', Y_k)$$

conditional probability distributions

$$\mu_k(dx) = \mathbb{P}[X_k \in dx \mid Y_{0:k}] \quad \text{and} \quad \mu_{k|k-1}(dx) = \mathbb{P}[X_k \in dx \mid Y_{0:k-1}]$$

going from  $\mu_{k-1}$  to  $\mu_k$  : decomposition into prediction / correction steps

$$\mu_{k-1} \xrightarrow{\text{prediction}} \mu_{k|k-1} = \mu_{k-1} Q_k \xrightarrow{\text{correction}} \mu_k = \Psi_k \cdot \mu_{k|k-1}$$

where  $\cdot$  denotes projective product, i.e.

$$\mu_k = \Psi_k \cdot \mu_{k|k-1} = \frac{\Psi_k \mu_{k|k-1}}{\mu_{k|k-1}(\Psi_k)}$$

or in a single step, introducing  $R_k(x, dx') = Q_k(x, dx') \Psi_k(x')$

$$\mu_{k-1} \longrightarrow \mu_k = \bar{R}_k(\mu_{k-1}) = \frac{\mu_{k-1} R_k}{(\mu_{k-1} R_k)(E)}$$

indeed

$$(\mu_{k-1} R_k)(dx') = \underbrace{\int_E \mu_{k-1}(dx) Q_k(x, dx') \Psi_k(x')}_{\mu_{k|k-1}(dx')}$$

and

$$(\mu_{k-1} R_k)(E) = \int_E \mu_{k|k-1}(dx') \Psi_k(x') = \mu_{k|k-1}(\Psi_k)$$

log-likelihood function

$$\ell_n = \sum_{k=1}^n \log \mu_{k|k-1}(\Psi_k) = \sum_{k=1}^n \log(\mu_{k-1} R_k)(E)$$

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- contrast functions in HMM
- **interacting particle approximation**
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recall that

$$\mu_{k-1} \longrightarrow \mu_k = \bar{R}_k(\mu_{k-1}) = \frac{\mu_{k-1} R_k}{(\mu_{k-1} R_k)(E)}$$

approximation : weighted empirical distribution

$$\mu_k \approx \mu_k^N = \sum_{i=1}^N w_k^i \delta_{\xi_k^i} \quad \text{with} \quad \sum_{i=1}^N w_k^i = 1$$

associated with particle system  $\Sigma_k = \{(\xi_k^i, w_k^i), i = 1 \dots N\}$

arbitrary **importance** decomposition of nonnegative kernel into

$$R_k(x, dx') = P_k(x, dx') W_k(x, x')$$

with

- Markov mutation kernel  $P_k(x, dx')$ , easy to **simulate** from
- selection function  $W_k(x, x')$ , easy to **evaluate**

a natural importance decomposition is available

$$R_k(x, dx') = Q_k(x, dx') \Psi_k(x')$$

example : sampling the solution of an SDE

$$dX'_t = b(X'_t) dt + \sigma(X'_t) dW'_t$$

at discrete time instants  $t_0 < \dots < t_k < \dots$ , yields a Markov chain  $X_k = X'_{t_k}$

no explicit expression is available in general for the Markov kernel

$$Q_k(x, dx') = \mathbb{P}[X_k \in dx' \mid X_{k-1} = x] = \mathbb{P}[X'_{t_k} \in dx' \mid X'_{t_{k-1}} = x]$$

but it is easy to **simulate** the r.v.  $X_k$  given  $X_{k-1} = x$  :

use any discretization scheme of the SDE between time instants  $t_{k-1}$  and  $t_k$ ,  
with initial condition  $X'_{t_{k-1}} = x$  □



starting from particle approximation

$$\mu_{k-1} \approx \mu_{k-1}^N = \sum_{i=1}^N w_{k-1}^i \delta_{\xi_{k-1}^i}$$

and applying nonnegative kernel  $R_k(x, dx')$  exactly, yields

$$\begin{aligned} (\mu_{k-1}^N R_k)(dx') &= \sum_{i=1}^N w_{k-1}^i R_k(\xi_{k-1}^i, dx') \\ &= \sum_{i=1}^N \underbrace{\frac{w_{k-1}^i}{\pi_k^i} W_k(\xi_{k-1}^i, x')}_{w_k^i(x')} \underbrace{\pi_k^i P_k(\xi_{k-1}^i, dx')}_{m_k^i(dx')} \end{aligned}$$

with arbitrary importance decomposition of discrete weights into

$$w_{k-1}^i = \frac{w_{k-1}^i}{\pi_k^i} \pi_k^i$$

**auxiliary particle** idea of Pitt and Shephard : sample product space  $E \times \{1 \cdots N\}$

SIR (sampling / importance resampling) algorithm

going from  $\Sigma_{k-1}$  to  $\Sigma_k$

- **selection** of particles with higher weights : independently for  $i = 1 \cdots N$

$$\tau_k^i \sim (\pi_k^1 \cdots \pi_k^N) \quad \text{with values in index set } \{1 \cdots N\}$$

- **mutation** using importance Markov kernel : independently for  $i = 1 \cdots N$

$$\xi_k^i \sim P_k(\xi_{k-1}^{\tau_k^i}, dx')$$

- **weighting** according to importance weight : for  $i = 1 \cdots N$

$$w_k^i = \frac{1}{c_k^N} \frac{w_{k-1}^{\tau_k^i}}{\pi_k^{\tau_k^i}} W_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i) \quad \text{s.t.} \quad \sum_{k=1}^N w_k^i = 1$$

discrete weights  $(w_{k-1}^1 \cdots w_{k-1}^N)$  are used for selection and / or weighting

particle approximation of log-likelihood function

$$\ell_n = \sum_{k=0}^n \log(\mu_{k-1} R_k)(E)$$

using SIR algorithm

$$\ell_n \approx \ell_n^N = \sum_{k=0}^n \log \left[ \frac{1}{N} \sum_{i=1}^N \frac{w_{k-1}^{\tau_k^i}}{\pi_k^i} W_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i) \right] = \sum_{k=0}^n \log \left[ \frac{1}{N} c_k^N \right]$$

alternatively, using simple bootstrap algorithm

$$\ell_n \approx \ell_n^N = \sum_{k=0}^n \log \left[ \frac{1}{N} \sum_{i=1}^N \Psi_k(\xi_k^i) \right]$$

unfortunately, particle systems  $\{\Sigma_k, 0 \leq k \leq n\}$  depend on the parameter

→ **pointwise**, irregular, Monte Carlo approximation of log-likelihood function

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define  $R_k^0(x, dx')$ , for some pivot (nominal) parameter value  $\theta_0 \in \Theta$

**Assumption AC<sub>0</sub>**

$$R_k(x, dx') = r_k(x, x') R_k^0(x, dx')$$

example : if

$$Q_k(x, dx') = q_k(x, x') Q_k^0(x, dx') \quad (\star)$$

then

$$R_k(x, dx') = Q_k(x, dx') \Psi_k(x') = \underbrace{q_k(x, x') \frac{\Psi_k(x')}{\Psi_k^0(x')}}_{r_k(x, x')} \underbrace{Q_k^0(x, dx') \Psi_k^0(x')}_{R_k^0(x, dx')}$$

i.e. Assumption AC<sub>0</sub> holds

remark : assumption  $(\star)$  is equivalent to

$$\mathbb{E}[\phi(X_k) \mid X_{k-1} = x] = \mathbb{E}^0[\phi(X_k) \Lambda_k \mid X_{k-1} = x] \quad (\star\star)$$

for any test function  $\phi$ , and for some (nonunique) r.v.  $\Lambda_k$

indeed, if  $(\star)$  holds, then

$$\begin{aligned} \mathbb{E}[\phi(X_k) \mid X_{k-1} = x] &= \int_E Q_k(x, dx') \phi(x') \\ &= \int_E Q_k^0(x, dx') q_k(x, x') \phi(x') \\ &= \mathbb{E}^0[\phi(X_k) q_k(X_{k-1}, X_k) \mid X_{k-1} = x] \end{aligned}$$

i.e.  $(\star\star)$  holds with

$$\Lambda_k = q_k(X_{k-1}, X_k)$$

conversely, if  $(\star\star)$  holds, then

$$\begin{aligned} \int_E Q_k(x, dx') \phi(x') &= \mathbb{E}[\phi(X_k) \mid X_{k-1} = x] \\ &= \mathbb{E}^0[\phi(X_k) \Lambda_k \mid X_{k-1} = x] \\ &= \int_E \mathbb{E}^0[\Lambda_k \mid X_{k-1} = x, X_k = x'] Q_k^0(x, dx') \phi(x') \end{aligned}$$

i.e.  $(\star)$  holds with

$$q_k(x, x') = \mathbb{E}^0[\Lambda_k \mid X_{k-1} = x, X_k = x']$$

even though no explicit expression is available in general for

$$q_k(x, x') = \mathbb{E}^0[\Lambda_k \mid X_{k-1} = x, X_k = x']$$

it may be easy to **simulate** jointly under  $\mathbb{P}^0$  the r.v.'s  $X_k$  and  $\Lambda_k$ , given  $X_{k-1} = x$

example (sampled SDE) :

$$dX'_t = b(X'_t) dt + \sigma(X'_t) dW'_t$$

if  $(b(x) - b^0(x))$  is in the range of  $\sigma(x)$ , and if  $\sigma(x)$  has full (column) rank, then  $\mathbb{P} \ll \mathbb{P}^0$ , with Radon–Nikodym derivative

$$\begin{aligned} \frac{d\mathbb{P}}{d\mathbb{P}^0} \Big|_{\mathcal{F}_t} &= \exp \left\{ \int_0^t [\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))]^* dW'_s{}^0 \right. \\ &\quad \left. - \frac{1}{2} \int_0^t |\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))|^2 ds \right\} \end{aligned}$$

with pseudo–inverse  $\sigma^+(x) = [\sigma^*(x) \sigma(x)]^{-1} \sigma^*(x)$ , hence under  $\mathbb{P}^0$

$$dX'_t = b_0(X'_t) dt + \sigma(X'_t) dW'_t{}^0$$



in addition

$$\Lambda_k = \exp \left\{ \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))]^* dW'_s{}^0 - \frac{1}{2} \int_{t_{k-1}}^{t_k} |\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))|^2 ds \right\}$$

and it is easy to simulate jointly under  $\mathbb{P}^0$  the r.v.'s  $X_k = X'_{t_k}$  and  $\Lambda_k$ ,  
given  $X'_{t_{k-1}} = x$   $\square$

recall that

$$\mu_{k-1} \longrightarrow \mu_k = \bar{R}_k(\mu_{k-1}) = \frac{\mu_{k-1} R_k}{(\mu_{k-1} R_k)(E)}$$

smooth approximation : weighted empirical distribution

$$\mu_k \approx \mu_k^N = \sum_{i=1}^N u_k^i w_k^{0,i} \delta_{\xi_k^{0,i}} \quad \text{with} \quad \sum_{i=1}^N w_k^{0,i} = 1 \quad \text{and} \quad \sum_{i=1}^N u_k^i w_k^{0,i} = 1$$

associated with

- unique particle system  $\Sigma_k^0 = \{(\xi_k^{0,i}, w_k^{0,i}), i = 1 \dots N\}$  defined using the pivot (nominal) value  $\theta_0$  only, i.e. independent of  $\theta$
- secondary weights  $S_k = \{u_k^i, i = 1 \dots N\}$  depending on  $\theta$

unique source of randomness (from Monte Carlo simulation, including interaction)

can expect smooth approximation, if secondary weights are smooth (continuous, differentiable, etc.) w.r.t. parameter

how is this possible ? starting from particle approximation

$$\mu_{k-1} \approx \mu_{k-1}^N = \sum_{i=1}^N u_{k-1}^i w_{k-1}^{0,i} \delta_{\xi_{k-1}^{0,i}}$$

and applying nonnegative kernel  $R_k(x, dx')$  exactly, with decomposition

$$R_k(x, dx') = r_k(x, x') R_k^0(x, dx') = r_k(x, x') W_k^0(x, x') P_k^0(x, dx')$$

under Assumption AC<sub>0</sub>, yields

$$\begin{aligned} (\mu_{k-1}^N R_k)(dx') &= \sum_{i=1}^N u_{k-1}^i w_{k-1}^{0,i} R_k(\xi_{k-1}^{0,i}, dx') \\ &= \sum_{i=1}^N \underbrace{u_{k-1}^i r_k(\xi_{k-1}^{0,i}, x')}_{r_k^i(x')} \underbrace{\frac{w_{k-1}^{0,i}}{\pi_k^{0,i}} W_k^0(\xi_{k-1}^{0,i}, x')}_{w_k^{0,i}(x')} \underbrace{\pi_k^{0,i} P_k^0(\xi_{k-1}^{0,i}, dx')}_{m_k^{0,i}(dx')} \end{aligned}$$

same auxiliary particle idea as above

smooth SIR (sampling / importance resampling) algorithm

going from  $(\Sigma_{k-1}^0, S_{k-1})$  to  $(\Sigma_k^0, S_k)$

- **selection** of particles with higher weights : independently for  $i = 1 \cdots N$

$$\tau_k^{0,i} \sim (\pi_k^{0,1} \cdots \pi_k^{0,N}) \quad \text{with values in index set } \{1 \cdots N\}$$

- **mutation** using importance Markov kernel : independently for  $i = 1 \cdots N$

$$\xi_k^{0,i} \sim P_k^0(\xi_{k-1}^{0,\tau_k^{0,i}}, dx')$$

- **weighting** according to importance weight : for  $i = 1 \cdots N$

$$w_k^{0,i} = \frac{1}{c_k^{0,N}} \frac{w_{k-1}^{0,\tau_k^{i,0}}}{\pi_k^{0,\tau_k^{i,0}}} W_k^0(\xi_{k-1}^{0,\tau_k^{i,0}}, \xi_k^{0,i}) \quad \text{s.t.} \quad \sum_{k=1}^N w_k^{0,i} = 1$$

- **updating** secondary weights : for  $i = 1 \cdots N$

$$u_k^i = \frac{1}{b_k^N} u_{k-1}^{\tau_k^{0,i}} r_k(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) \quad \text{s.t.} \quad \sum_{k=1}^N u_k^i w_k^{0,i} = 1$$

particle approximation of log-likelihood function

$$\ell_n = \sum_{k=0}^n \log(\mu_{k-1} R_k)(E)$$

using SIR algorithm

$$\begin{aligned} \ell_n \approx \ell_n^N &= \sum_{k=0}^n \log \left[ \frac{1}{N} \sum_{i=1}^N u_{k-1}^{\tau_k^{0,i}} r_k(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) \frac{w_{k-1}^{0,\tau_k^{0,i}}}{\pi_k^{0,\tau_k^{0,i}}} W_k^0(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) \right] \\ &= \sum_{k=0}^n \log \left[ \frac{1}{N} \sum_{i=1}^N \frac{w_{k-1}^{0,\tau_k^{0,i}}}{\pi_k^{0,\tau_k^{0,i}}} W_k^0(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) \sum_{i=1}^N u_{k-1}^{\tau_k^{0,i}} r_k(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) w_k^{0,i} \right] \\ &= \sum_{k=0}^n \log \left[ \frac{1}{N} c_k^{0,N} \right] + \sum_{k=0}^n \log b_k^N \end{aligned}$$

particle systems  $\{\Sigma_k^0, 0 \leq k \leq n\}$  do not depend on the parameter

→ **global**, possibly regular, Monte Carlo approximation of log-likelihood function

convergence result : under technical assumptions

- on the model, including Lipschitz continuity of  $\theta \longmapsto r_k(x, x')$  in some sense
- on the importance decomposition of kernels

it holds

$$\sup_{\|\phi\|=1} \left\{ \mathbb{E} \left[ \sup_{\theta \in \Theta} |\mu_n^N(\phi) - \mu_n(\phi)|^p \right] \right\}^{1/p} \leq \frac{C_{p,n}}{\sqrt{N}}$$

and

$$\left\{ \mathbb{E} \left[ \sup_{\theta \in \Theta} |\ell_n^N - \ell_n|^p \right] \right\}^{1/p} \leq \frac{C_{p,n}}{\sqrt{N}}$$

hence, almost surely as  $N \rightarrow \infty$

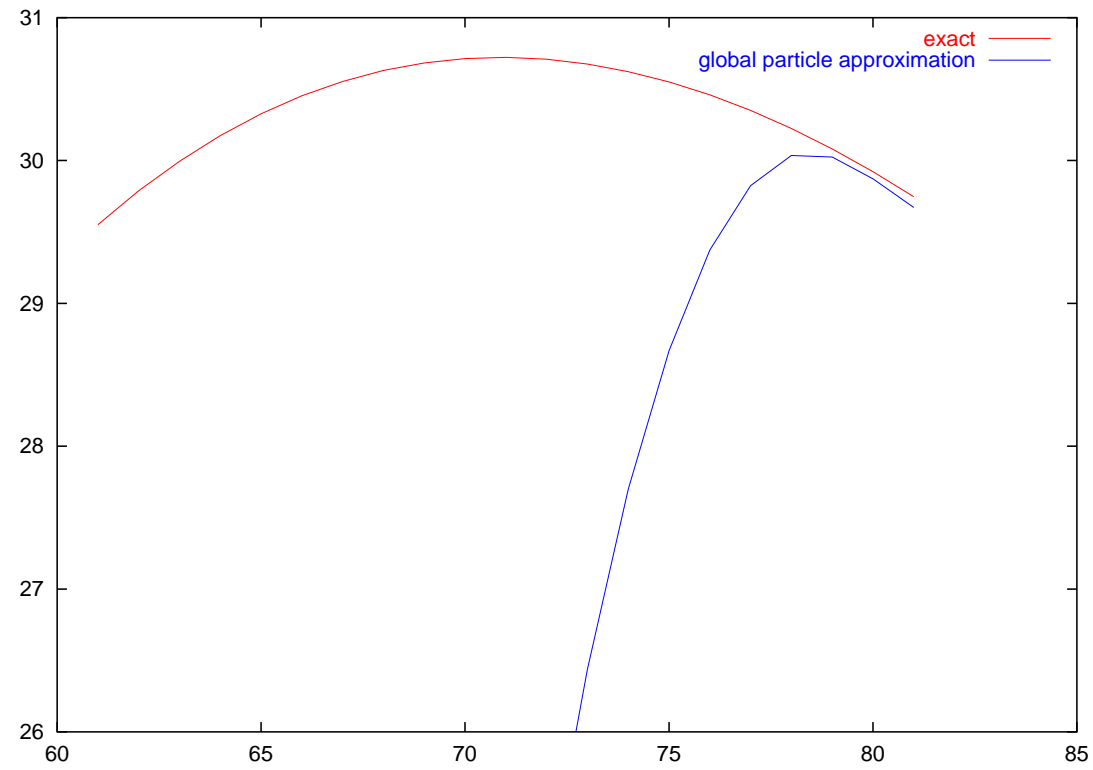
$$\sup_{\theta \in \Theta} |\ell_n^N - \ell_n| \longrightarrow 0$$

and

$$\widehat{\theta}_n^N = \operatorname{argmax}_{\theta \in \Theta} \ell_n^N \longrightarrow \operatorname{argmax}_{\theta \in \Theta} \ell_n = \widehat{\theta}_n$$

interacting particle implementation of the MCML algorithm of Geyer (1994, 1996)

## numerical example



## comments

- for values of parameter too much away from pivot (nominal) value, essentially weighted Monte Carlo approximation, without interaction : poor approximation, already noticed by Cappé, Douc, Moulines and Robert (2002)
- local (in the vicinity of pivot (nominal) value, if not global) vs. pointwise particle approximation
- can expect smooth approximation, if secondary weights are smooth (continuous, differentiable, etc.) w.r.t. parameter



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nonnegative kernels  $R_k(x, dx')$  differentiable w.r.t. parameter  $\theta$

**Assumption AC**

$$\frac{\partial}{\partial \theta} R_k(x, dx') = s_k(x, x') R_k(x, dx')$$

remark : if Assumption  $AC_0$  holds, i.e. if

$$R_k(x, dx') = r_k(x, x') R_k^0(x, dx')$$

and if functions  $r_k(x, x')$  are differentiable w.r.t. parameter  $\theta$

then Assumption AC holds, with

$$s_k(x, x') = \frac{\partial}{\partial \theta} \log r_k(x, x')$$

remark : recall that, if

$$Q_k(x, dx') = q_k(x, x') Q_k^0(x, dx') \quad (\star)$$

then Assumption AC<sub>0</sub> holds, with

$$r_k(x, x') = q_k(x, x') \frac{\Psi_k(x')}{\Psi_k^0(x')}$$

hence if functions  $q_k(x, x')$  and  $\Psi_k(x')$  are differentiable w.r.t. parameter  $\theta$

then Assumption AC holds, with

$$s_k(x, x') = \frac{\partial}{\partial \theta} \log r_k(x, x') = \frac{\partial}{\partial \theta} \log q_k(x, x') + \frac{\partial}{\partial \theta} \log \Psi_k(x')$$

alternatively, if

$$\int_E Q_k(x, dx') \phi(x') = \mathbb{E}[\phi(X_k) \mid X_{k-1} = x] = \mathbb{E}^0[\phi(X_k) \Lambda_k \mid X_{k-1} = x] \quad (**)$$

for any test function  $\phi$ , and for some (nonunique) r.v.  $\Lambda_k$ , then

$$\begin{aligned} \int_E \frac{\partial}{\partial \theta} Q_k(x, dx') \phi(x') &= \mathbb{E}^0[\phi(X_k) \Lambda_k \frac{\partial}{\partial \theta} \log \Lambda_k \mid X_{k-1} = x] \\ &= \mathbb{E}[\phi(X_k) \frac{\partial}{\partial \theta} \log \Lambda_k \mid X_{k-1} = x] \\ &= \int_E \mathbb{E}[\frac{\partial}{\partial \theta} \log \Lambda_k \mid X_{k-1} = x, X_k = x'] Q_k(x, dx') \phi(x') \end{aligned}$$

i.e.

$$\frac{\partial}{\partial \theta} Q_k(x, dx') = I_k(x, x') Q_k(x, dx')$$

with

$$I_k(x, x') = \mathbb{E}[\frac{\partial}{\partial \theta} \log \Lambda_k \mid X_{k-1} = x, X_k = x']$$

and

$$\begin{aligned} \frac{\partial}{\partial \theta} R_k(x, dx') &= \left[ \frac{\partial}{\partial \theta} Q_k(x, dx') + Q_k(x, dx') \frac{\partial}{\partial \theta} \log \Psi_k(x') \right] \Psi_k(x') \\ &= \left[ I_k(x, x') + \frac{\partial}{\partial \theta} \log \Psi_k(x') \right] R_k(x, dx') \end{aligned}$$

i.e. Assumption AC holds, with

$$s_k(x, x') = I_k(x, x') + \frac{\partial}{\partial \theta} \log \Psi_k(x')$$

even though no explicit expression is available in general for

$$I_k(x, x') = \mathbb{E} \left[ \frac{\partial}{\partial \theta} \log \Lambda_k \mid X_{k-1} = x, X_k = x' \right]$$

it may be easy to **simulate** jointly under  $\mathbb{P}$  the r.v.'s  $X_k$  and  $\frac{\partial}{\partial \theta} \log \Lambda_k$ , given  $X_{k-1} = x$

example (sampled SDE) :

$$dX'_t = b(X'_t) dt + \sigma(X'_t) dW'_t$$

recall that, if  $(b(x) - b^0(x))$  is in the range of  $\sigma(x)$ , and if  $\sigma(x)$  has full (column) rank, then

$$\Lambda_k = \exp \left\{ \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))]^* dW'_s \right. \\ \left. - \frac{1}{2} \int_{t_{k-1}}^{t_k} |\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))|^2 ds \right\}$$

therefore

$$\begin{aligned}
\frac{\partial}{\partial \theta} \log \Lambda_k &= \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) \frac{\partial}{\partial \theta} b(X'_s)]^* dW_s'^0 \\
&\quad - \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) \frac{\partial}{\partial \theta} b(X'_s)]^* [\sigma^+(X'_s) (b(X'_s) - b^0(X'_s))] ds \\
&= \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) \frac{\partial}{\partial \theta} b(X'_s)]^* [dW_s'^0 - \sigma^+(X'_s) (b(X'_s) - b^0(X'_s)) ds] \\
&= \int_{t_{k-1}}^{t_k} [\sigma^+(X'_s) \frac{\partial}{\partial \theta} b(X'_s)]^* dW_s'
\end{aligned}$$

and it is easy to **simulate** jointly under  $\mathbb{P}$  the r.v.'s  $X_k = X'_{t_k}$  and  $\frac{\partial}{\partial \theta} \log \Lambda_k$ ,  
given  $X'_{t_{k-1}} = x$   $\square$

recall that

$$\mu_k \approx \mu_k^N = \sum_{i=1}^N u_k^i w_k^{0,i} \delta_{\xi_k^{0,i}} \quad \text{with} \quad \sum_{i=1}^N w_k^{0,i} = 1$$

and

$$u_k^i = \frac{1}{b_k^N} u_{k-1}^{\tau_k^{0,i}} r_k(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) \quad \text{s.t.} \quad \sum_{k=1}^N u_k^i w_k^{0,i} = 1$$

under Assumption AC, secondary weights are differentiable w.r.t. parameter  $\theta$ , hence particle approximation is differentiable w.r.t. parameter  $\theta$ , with derivative

$$\dot{\mu}_k^N = \frac{\partial}{\partial \theta} \mu_k^N = \sum_{i=1}^N \rho_k^i w_k^{0,i} \delta_{\xi_k^{0,i}} \quad \text{with} \quad \sum_{k=1}^N \rho_k^i w_k^{0,i} = 0$$

where (using logarithmic derivatives)

$$\rho_k^i = \frac{\partial}{\partial \theta} u_k^i = \left[ \frac{\tau_k^{0,i}}{u_{k-1}^{\tau_k^{0,i}}} + s_k(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) - a_k^N \right] u_k^i$$



at pivot (nominal) value  $\theta_0$ , it holds

$$\dot{\mu}_k^{0,N} = \left. \frac{\partial}{\partial \theta} \mu_k^N \right|_{\theta=\theta_0} = \sum_{i=1}^N \rho_k^{0,i} w_k^{0,i} \delta_{\xi_k^{0,i}} \quad \text{s.t.} \quad \sum_{k=1}^N \rho_k^{0,i} w_k^{0,i} = 0$$

where, taking  $u_k^{0,i} \equiv 1$  into account

$$\rho_k^{0,i} = \left. \frac{\partial}{\partial \theta} u_k^i \right|_{\theta=\theta_0} = \rho_{k-1}^{0,\tau_k^{0,i}} + s_k^0(\xi_{k-1}^{0,\tau_k^{0,i}}, \xi_k^{0,i}) - a_k^{0,N}$$

questions

- is the optimal filter differentiable w.r.t. parameter (e.g. under Assumption AC) ?
- does the derivative of the smooth particle approximation provide a reasonable approximation of the linear tangent filter ?

## Plan

- contrast functions in HMM
- interacting particle approximation
- global interacting particle approximation
- smooth interacting particle approximation
- **linear tangent filter**
- linear tangent filter : interacting particle approximation
- conclusion

recall that

$$\mu_{k-1} \longrightarrow \mu_k = \bar{R}_k(\mu_{k-1}) = \frac{\mu_{k-1} R_k}{(\mu_{k-1} R_k)(E)}$$

if Assumption AC holds, i.e. if

$$\frac{\partial}{\partial \theta} R_k(x, dx') = s_k(x, x') R_k(x, dx')$$

then

$$(\mu_{k-1} \frac{\partial}{\partial \theta} R_k)(dx') = \int_E \mu_{k-1}(dx) s_k(x, x') R_k(x, dx')$$

and  $\{\mu_k, k \geq 0\}$  is differentiable w.r.t. parameter, with derivative  $\{\dot{\mu}_k, k \geq 0\}$  given by linear tangent equation

$$(\mu_{k-1}, \dot{\mu}_{k-1}) \longrightarrow \dot{\mu}_k = \frac{\dot{\mu}_{k-1} R_k + \mu_{k-1} \frac{\partial}{\partial \theta} R_k}{(\mu_{k-1} R_k)(E)} - a_k \mu_k$$

with constant  $a_k$  s.t. signed measure  $\dot{\mu}_k$  has zero total mass

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by induction  $\dot{\mu}_k \ll \mu_k$

joint approximation : weighted empirical distributions

$$\mu_k \approx \mu_k^N = \sum_{i=1}^N w_k^i \delta_{\xi_k^i} \quad \text{with} \quad \sum_{i=1}^N w_k^i = 1$$

$$\dot{\mu}_k \approx \dot{\mu}_k^N = \sum_{i=1}^N \rho_k^i w_k^i \delta_{\xi_k^i} \quad \text{with} \quad \sum_{i=1}^N \rho_k^i w_k^i = 0$$

associated with

- unique particle system  $\Sigma_k = \{(\xi_k^i, w_k^i), i = 1 \cdots N\}$
- signed weights  $S'_k = \{\rho_k^i, i = 1 \cdots N\}$

starting from particle approximations

$$\mu_{k-1} \approx \mu_{k-1}^N = \sum_{i=1}^N w_{k-1}^i \delta_{\xi_{k-1}^i}$$

$$\dot{\mu}_{k-1} \approx \dot{\mu}_{k-1}^N = \sum_{i=1}^N \rho_{k-1}^i w_{k-1}^i \delta_{\xi_{k-1}^i}$$

and applying nonnegative kernels  $R_k(x, dx')$  and  $\frac{\partial}{\partial \theta} R_k(x, dx')$  exactly, yields

$$\begin{aligned} (\mu_{k-1}^N R_k)(dx') &= \sum_{i=1}^N w_{k-1}^i R_k(\xi_{k-1}^i, dx') \\ &= \sum_{i=1}^N \underbrace{\frac{w_{k-1}^i}{\pi_k^i} W_k(\xi_{k-1}^i, x')}_{w_k^i(x')} \underbrace{\pi_k^i P_k(\xi_{k-1}^i, dx')}_{m_k^i(dx')} \end{aligned}$$

and

$$\begin{aligned}
 & (\dot{\mu}_{k-1}^N R_k + \mu_{k-1}^N \frac{\partial}{\partial \theta} R_k)(dx') \\
 &= \sum_{i=1}^N w_{k-1}^i [\rho_{k-1}^i + s_k(\xi_{k-1}^i, x')] R_k(\xi_{k-1}^i, dx') \\
 &= \sum_{i=1}^N \underbrace{\frac{w_{k-1}^i}{\pi_k^i} W_k(\xi_{k-1}^i, x')}_{w_k^i(x')} \underbrace{[\rho_{k-1}^i + s_k(\xi_{k-1}^i, x')]}_{r_k^i(x')} \underbrace{\pi_k^i P_k(\xi_{k-1}^i, dx')}_{m_k^i(dx')}
 \end{aligned}$$

under Assumption AC

same auxiliary particle idea as above

joint SIR (sampling / importance resampling) algorithm

going from  $(\Sigma_{k-1}, S'_{k-1})$  to  $(\Sigma_k, S'_k)$

- **selection** of particles with higher weights : independently for  $i = 1 \dots N$

$$\tau_k^i \sim (\pi_k^1 \dots \pi_k^N) \quad \text{with values in index set } \{1 \dots N\}$$

- **mutation** using importance Markov kernel : independently for  $i = 1 \dots N$

$$\xi_k^i \sim P_k(\xi_{k-1}^{\tau_k^i}, dx')$$

- **weighting** according to importance weight : for  $i = 1 \dots N$

$$w_k^i = \frac{1}{c_k^N} \frac{w_{k-1}^{\tau_k^i}}{\pi_k^{\tau_k^i}} W_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i) \quad \text{s.t.} \quad \sum_{k=1}^N w_k^i = 1$$

- **updating** signed weights : for  $i = 1 \dots N$

$$\rho_k^i = \rho_{k-1}^{\tau_k^i} + s_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i) - a_k^N \quad \text{s.t.} \quad \sum_{k=1}^N \rho_k^i w_k^i = 0$$



particle approximation of score function

recall expression for log-likelihood function

$$\ell_n = \sum_{k=0}^n \log(\mu_{k-1} R_k)(E)$$

hence

$$\frac{\partial}{\partial \theta} \ell_n = \sum_{k=0}^n \frac{(\dot{\mu}_{k-1} R_k + \mu_{k-1} \frac{\partial}{\partial \theta} R_k)(E)}{(\mu_{k-1} R_k)(E)}$$

using SIR algorithm

$$\ell_n \approx \ell_n^N = \sum_{k=0}^n \log \left[ \frac{1}{N} \sum_{i=1}^N \frac{w_{k-1}^{\tau_k^i}}{\pi_k^{\tau_k^i}} W_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i) \right] = \sum_{k=0}^n \log \left[ \frac{1}{N} c_k^N \right]$$

and

$$\frac{\partial}{\partial \theta} \ell_n \approx \frac{\partial}{\partial \theta} \ell_n^N = \sum_{k=0}^n \sum_{i=1}^N w_k^i [\rho_{k-1}^{\tau_k^i} + s_k(\xi_{k-1}^{\tau_k^i}, \xi_k^i)] = \sum_{k=0}^n a_k^N$$

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## conclusion

- two different approaches to obtain interacting particle approximation of linear tangent filter
- more general version, under weaker form of Assumptions  $AC_0$  and  $AC$  (no explicit expression for  $r_k(x, x')$  and  $s_k(x, x')$ )

## references and some related work

- particle and Monte Carlo approximation of log-likelihood function : Sørensen (PhD thesis 2000, 2003), Hürzeler and Künsch (2001)
- pointwise interacting particle approximation of linear tangent filter : Cérrou, Le Gland and Newton (2001)
- interacting particle approximation of recursive MLE : Guyader, Le Gland and Oudjane (2003), Doucet and Tadić (2003)
- global interacting particle approximation of linear tangent filter : Caylus, Guyader, Le Gland and Oudjane (2004)
- interacting particle (or MCMC) implementation of fully Bayesian approach : dominant approach, with many contributions, including recently Papavasiliou (PhD thesis 2002, 2003), Rossi (PhD thesis 2004)