Drift parameter estimation in models with fractional Brownian motion by discrete observations

Kostiantyn Ralchenko, Yuliya Mishura

Taras Shevchenko National University of Kyiv

17 March 2015

#### Outline

## Introduction

### Model description

- Fractional Brownian motion
- Fractional derivatives
- Stochastic differential equation
- Assumptions

## 3 Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case a = b

### 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

## 5 Estimates for fractional derivatives of fBm and for solutions of SDE

# Introduction

- Model description
  - Fractional Brownian motion
  - Fractional derivatives
  - Stochastic differential equation
  - Assumptions

### 3 Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case *a* = *b*

### 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

### 5 Estimates for fractional derivatives of fBm and for solutions of SDE

Stochastic differential equations driven by a fractional Brownian motion have been a subject of an active research for the last two decades. Main reason is that such equations seem to be one of the most suitable tools to model long-range dependence in many applied areas, such as physics, finance, biology, network studies etc.

This talk deals with statistical estimation of drift parameter for a stochastic differential equation with fBm by discrete observation of its solution. We propose three new estimators and prove their strong consistency under the so-called "high-frequency data" assumption that the horizon of observations tends to infinity, while the interval between them goes to zero. Moreover, we obtain almost sure upper bounds for the rate of convergence of the estimators. The estimators proposed go far away from being maximum likelihood estimators, and this is their crucial advantage, because they keep strong consistency but they are not complicated technically and are convenient for the simulations.

イロト 不得下 イヨト イヨト

### Introduction

## Model description

- Fractional Brownian motion
- Fractional derivatives
- Stochastic differential equation
- Assumptions

### Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case a = b

## 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

### 5 Estimates for fractional derivatives of fBm and for solutions of SDE

Fractional Brownian motion (fBm) with Hurst parameter  $H \in (0, 1)$  is a centered Gaussian process  $\{B_t^H, t \ge 0\}$  on a complete probability space  $(\Omega, \mathcal{F}, \mathsf{P})$  with the covariance

$$\mathsf{E}\left[B_{t}^{H}B_{s}^{H}\right] = \frac{1}{2}(s^{2H} + t^{2H} - |t - s|^{2H}).$$

It is well known that  $B^H$  has a modification with almost surely continuous paths (even Hölder continuous of any order up to H), and further we will assume that it is continuous itself.

In what follows we assume that the Hurst parameter  $H \in (1/2, 1)$  is fixed.

In this case, the integral with respect to the fBm  $B^H$  will be understood in the generalized Lebesgue–Stieltjes sense. Its construction uses the fractional derivatives, defined for a < b and  $\alpha \in (0, 1)$  as

$$(D_{a+}^{\alpha}f)(x) = \frac{1}{\Gamma(1-\alpha)} \left(\frac{f(x)}{(x-a)^{\alpha}} + \alpha \int_{a}^{\hat{r}} \frac{f(x) - f(u)}{(x-u)^{1+\alpha}} du\right),$$
$$(D_{b-}^{1-\alpha}g)(x) = \frac{e^{-i\pi\alpha}}{\Gamma(\alpha)} \left(\frac{g(x)}{(b-x)^{1-\alpha}} + (1-\alpha) \int_{x}^{b} \frac{g(x) - g(u)}{(u-x)^{2-\alpha}} du\right).$$

Provided that  $D_{a+}^{\alpha}f \in L_1[a, b]$ ,  $D_{b-}^{1-\alpha}g_{b-} \in L_{\infty}[a, b]$ , where  $g_{b-}(x) = g(x) - g(b)$ , the generalized Lebesgue-Stieltjes integral  $\int_{a}^{b} f(x)dg(x)$  is defined as

$$\int_{a}^{b} f(x) dg(x) = e^{i\pi\alpha} \int_{a}^{b} (D_{a+}^{\alpha} f)(x) (D_{b-}^{1-\alpha} g_{b-})(x) dx.$$
(1)

It follows from Hölder continuity of  $B^H$  that for  $\alpha \in (1 - H, 1)$  $D_{b-}^{1-\alpha}B_{b-}^H \in L_{\infty}[a, b]$  a.s. Then for a function f with  $D_{a+}^{\alpha}f \in L_1[a, b]$  we can define integral with respect to  $B^H$  through (1):

$$\int_{a}^{b} f(x) \, dB^{H}(x) := e^{i\pi\alpha} \int_{a}^{b} (D_{a+}^{\alpha}f)(x) (D_{b-}^{1-\alpha}B_{b-}^{H})(x) \, dx.$$
(2)

・ロト ・得ト ・ヨト ・ヨト

Consider the stochastic differential equation driven by fractional Brownian motion  $B^{H}$ :

$$dX_t = \theta a(t, X_t) dt + b(t, X_t) dB_t^H, \quad 0 \le t \le T, \quad T > 0,$$
  
$$X|_{t=0} = X_0 \in \mathbb{R}.$$
(3)

Here  $\theta \in \mathbb{R}$  is unknown parameter to be estimated.

イロト 不得下 イヨト イヨト 二日

Assume that the following conditions hold:

(1) there exist positive constants  $C_1$ ,  $C_2$  such that for all  $t \in [0, T]$ ,  $x, y \in \mathbb{R}$ 

$$egin{aligned} |a(t,x)-a(t,y)|+|b(t,x)-b(t,y)|&\leq C_1\,|x-y|\,,\ &|a(t,x)|+|b(t,x)|&\leq C_2(1+|x|); \end{aligned}$$

(II) there exist constants  $C_3 > 0$  and  $\rho \in \left(\frac{1}{H} - 1, 1\right)$  such that for all  $t \in [0, T]$ ,  $x, y \in \mathbb{R}$ 

$$\left|b_x^\prime(t,x)-b_y^\prime(t,y)
ight|\leq C_3\left|x-y
ight|^
ho$$
 ;

(III) there exist constants  $C_4 > 0$  and  $\mu \in (1 - H, 1)$  such that for all  $t, s \in [0, T]$ ,  $x \in \mathbb{R}$ 

$$\left|b(t,x)-b(s,x)
ight|+\left|b_x'(t,x)-b_x'(s,x)
ight|\leq C_4\left|t-s
ight|^{\mu}.$$

Assume that the following conditions hold:

(1) there exist positive constants  $C_1$ ,  $C_2$  such that for all  $t \in [0, T]$ ,  $x, y \in \mathbb{R}$ 

$$egin{aligned} |a(t,x)-a(t,y)|+|b(t,x)-b(t,y)|&\leq C_1\,|x-y|\,,\ &|a(t,x)|+|b(t,x)|&\leq C_2(1+|x|); \end{aligned}$$

(II) there exist constants  $C_3 > 0$  and  $\rho \in \left(\frac{1}{H} - 1, 1\right)$  such that for all  $t \in [0, T]$ ,  $x, y \in \mathbb{R}$ 

$$\left|b_x'(t,x)-b_y'(t,y)
ight|\leq C_3\left|x-y
ight|^
ho$$
 ;

(III) there exist constants  $C_4 > 0$  and  $\mu \in (1 - H, 1)$  such that for all  $t, s \in [0, T], x \in \mathbb{R}$ 

$$\left|b(t,x)-b(s,x)
ight|+\left|b_x'(t,x)-b_x'(s,x)
ight|\leq C_4\left|t-s
ight|^{\mu}.$$

According to [Nualart,Rascanu(2002), Theorem 2.1], under the conditions (I)–(III) there exists a unique solution X of the stochastic equation (3).

In addition, suppose that the following conditions hold:

(IV) 
$$b(t,x) \neq 0$$
;  
(V)  $a, b \in C([0,\infty) \times \mathbb{R})$ .  
Denote  $\alpha = H - \frac{1}{2}$ ,  $\tilde{\alpha} = (1 - 2\alpha)^{-1}$ ,  $C_H = \left(\frac{\Gamma(2-2\alpha)}{2H\Gamma(1-\alpha)^3\Gamma(\alpha+1)}\right)^{\frac{1}{2}}$ ,  
 $l_H(t,s) = C_H s^{-\alpha}(t-s)^{-\alpha} l_{\{0 < s < t\}}$ ,  $\psi(t,x) = \frac{a(t,x)}{b(t,x)}$ ,  $\varphi(t) = \psi(t, X_t)$ ,  
 $l(t) = \int_0^t l_H(t,s)\varphi(s)ds$ .

3

イロト イポト イヨト イヨト

In addition, suppose that the following conditions hold:

(IV) 
$$b(t,x) \neq 0$$
;  
(V)  $a, b \in C([0,\infty) \times \mathbb{R})$ .  
Denote  $\alpha = H - \frac{1}{2}$ ,  $\tilde{\alpha} = (1 - 2\alpha)^{-1}$ ,  $C_H = \left(\frac{\Gamma(2-2\alpha)}{2H\Gamma(1-\alpha)^3\Gamma(\alpha+1)}\right)^{\frac{1}{2}}$ ,  
 $l_H(t,s) = C_H s^{-\alpha}(t-s)^{-\alpha} l_{\{0 < s < t\}}$ ,  $\psi(t,x) = \frac{a(t,x)}{b(t,x)}$ ,  $\varphi(t) = \psi(t, X_t)$ ,  
 $l(t) = \int_0^t l_H(t,s)\varphi(s)ds$ .  
Under the conditions (I), (III)–(V)  $\varphi(t), t \in [0, T]$  is a continuous process  
with probability 1. Hence, it is Lebesgue integrable and for each  $t \in [0, T]$   
there exists an integral  $\int_0^t l_H(t,s)\varphi(s)ds$ .

3

(日) (同) (日) (日) (日)

In addition, suppose that the following conditions hold:

(IV) 
$$b(t,x) \neq 0$$
;  
(V)  $a, b \in C([0,\infty) \times \mathbb{R})$ .  
Denote  $\alpha = H - \frac{1}{2}$ ,  $\tilde{\alpha} = (1 - 2\alpha)^{-1}$ ,  $C_H = \left(\frac{\Gamma(2-2\alpha)}{2H\Gamma(1-\alpha)^3\Gamma(\alpha+1)}\right)^{\frac{1}{2}}$ ,  
 $l_H(t,s) = C_H s^{-\alpha}(t-s)^{-\alpha} l_{\{0 < s < t\}}$ ,  $\psi(t,x) = \frac{a(t,x)}{b(t,x)}$ ,  $\varphi(t) = \psi(t, X_t)$ ,  
 $l(t) = \int_0^t l_H(t,s)\varphi(s)ds$ .  
Under the conditions (I), (III)–(V)  $\varphi(t), t \in [0, T]$  is a continuous process  
with probability 1. Hence, it is Lebesgue integrable and for each  $t \in [0, T]$   
there exists an integral  $\int_0^t l_H(t,s)\varphi(s)ds$ .  
Consider the new process  $\hat{B}_t^H := B_t^H + \theta \int_0^t \varphi(s)ds$ .

Suppose that the following assumptions hold.

(VI) There exists such function  $\delta$  that belongs to  $L_1[0, t]$  for all  $t \in [0, T]$ a.s. and satisfies the equation

$$heta\int\limits_{0}^{t}I_{H}(t,s)arphi(s)ds=(\widetilde{lpha})^{-1/2}\int\limits_{0}^{t}\delta_{s}ds;$$

 $\begin{array}{ll} (\text{VII}) & \text{E} \int_{0}^{t} s^{2\alpha} \delta_{s}^{2} ds < \infty, \ t \in [0, \ T]; \\ (\text{VIII}) & \text{E} \exp \left\{ L_{t} - \frac{1}{2} \langle L \rangle_{t} \right\} = 1, \ \text{where} \ L_{t} = \int_{0}^{t} s^{\alpha} \delta_{s} d\widehat{B}_{s}, \ \text{and} \ \widehat{B} \ \text{is Wiener} \\ & \text{process with respect to probability measure} \ \mathsf{P}_{0}(t) \ \text{corresponding to} \\ & \text{the zero drift such that} \end{array}$ 

$$\int_{0}^{t} I_{H}(t,s) d\widehat{B}_{s}^{H} = \widetilde{\alpha}^{-1/2} \int_{0}^{t} s^{-\alpha} d\widehat{B}_{s}.$$

### Introduction

### Model description

- Fractional Brownian motion
- Fractional derivatives
- Stochastic differential equation
- Assumptions

### 3 Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case a = b

### 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

### 5 Estimates for fractional derivatives of fBm and for solutions of SDE

We can present likelihood ratio as a function of the observed process  $X_t$ .

$$L_t = \int_0^t s^\alpha \delta_s d\widehat{B}_s = \int_0^t s^{2\alpha} \delta_s dY_s, \qquad (4)$$

where

$$Y_{s} = \int_{0}^{s} u^{-\alpha} d\widehat{B}_{u} = \widetilde{\alpha}^{1/2} \int_{0}^{s} I_{H}(s, u) b^{-1}(u, X_{u}) dX_{u},$$

$$\delta_{s} = \theta \widetilde{\alpha}^{1/2} \left( \int_{0}^{s} I_{H}(s, u) \varphi(u) du \right)' = C_{H} \theta \widetilde{\alpha}^{1/2} \left( \int_{0}^{s} (s - u)^{-\alpha} u^{-\alpha} \varphi(u) du \right)'$$
(6)

or

$$\delta_{s} = C_{H} \theta \widetilde{\alpha}^{1/2} \left( \frac{\varphi(s)}{s^{2\alpha}} + \alpha \int_{0}^{s} \frac{s^{-\alpha} \varphi(s) - u^{-\alpha} \varphi(u)}{(s-u)^{\alpha+1}} du \right).$$
(7)

Kostiantyn Ralchenko (Kyiv University) Parameter estimation in models with fBm

< /⊒ > <

According to [Mishura (2008), formula (6.3.13)], the maximum-likelihood estimator has the form

$$\hat{\theta}_t^{(1)} = \frac{\widetilde{\alpha}^{-1/2} \int_0^t s^\alpha l'(s) d\widehat{B}_s}{\int_0^t s^{2\alpha} (l'(s))^2 ds} = \frac{\theta L_t}{\int_0^t s^{2\alpha} \delta_s^2 ds}.$$
(8)

Using (4), (5), (7) and the definition of the kernel  $I_H(t,s)$  we can write

$$\begin{aligned} \hat{\theta}_t^{(1)} &= \frac{\theta \int_0^t s^{2\alpha} \delta_s dY_s}{\int_0^t s^{2\alpha} \delta_s^2 ds} \\ &= \frac{\int_0^t \left(\varphi(s) + \alpha s^{2\alpha} \int_0^s \frac{s^{-\alpha} \varphi(s) - u^{-\alpha} \varphi(u)}{(s-u)^{\alpha+1}} du\right) d(\int_0^s v^{-\alpha} (s-v)^{-\alpha} b^{-1}(v, X_v) dX_v)}{\int_0^t s^{2\alpha} \left(\frac{\varphi(s)}{s^{2\alpha}} + \alpha \int_0^s \frac{s^{-\alpha} \varphi(s) - u^{-\alpha} \varphi(u)}{(s-u)^{\alpha+1}} du\right)^2 ds \end{aligned}$$

#### Remark

According to [Mishura (2008), Theorem 6.3.3], under assumptions (I)–(VIII) and  $\int_0^{\infty} s^{2\alpha} (I'(s))^2 ds = \infty$  a.s. we have the convergence  $\hat{\theta}_T^{(1)} \xrightarrow{P1} \theta$ ,  $T \to \infty$ .

Let  $t_k^n = \frac{k}{2^n}$ ,  $k = 0, 1, 2, ..., 2^{2n}$ . We can define a discretized version of the maximum-likelihood estimator

$$\hat{\theta}_{n}^{(2)} := \frac{\sum_{k=0}^{2^{2n}-1} \left( \varphi(t_{k}^{n}) + \alpha(t_{k}^{n})^{2\alpha} \sum_{i=1}^{k-1} \frac{(t_{k}^{n})^{-\alpha}\varphi(t_{k}^{n}) - (t_{i}^{n})^{-\alpha}\varphi(t_{i}^{n})}{(t_{k}^{n}-t_{i}^{n})^{\alpha+1}2^{n}} \right) \left( \widetilde{Y}_{t_{k+1}}^{n} - \widetilde{Y}_{t_{k}}^{n} \right)}{\sum_{k=0}^{2^{2n}-1} (t_{k}^{n})^{2\alpha} \left( \frac{\varphi(t_{k}^{n})}{(t_{k}^{n})^{2\alpha}} + \alpha \sum_{i=1}^{k-1} \frac{(t_{k}^{n})^{-\alpha}\varphi(t_{k}^{n}) - t_{i}^{-\alpha}\varphi(t_{i}^{n})}{(t_{k}^{n}-t_{i}^{n})^{\alpha+1}} \frac{1}{2^{n}} \right)^{2} \frac{1}{2^{n}}}{(9)}$$

where

$$\widetilde{Y}_{t_k} = \sum_{i=1}^{k-1} (t_i^n)^{-\alpha} (t_k^n - t_i^n)^{-\alpha} b^{-1} (t_i^n, X_{t_i^n}) \left( X_{t_{i+1}^n} - X_{t_i^n} \right).$$

イロト 不得下 イヨト イヨト 二日

Let  $t_k^n = \frac{k}{2^n}$ ,  $k = 0, 1, 2, ..., 2^{2n}$ . We can define a discretized version of the maximum-likelihood estimator

$$\hat{\theta}_{n}^{(2)} := \frac{\sum_{k=0}^{2^{2n}-1} \left( \varphi(t_{k}^{n}) + \alpha(t_{k}^{n})^{2\alpha} \sum_{i=1}^{k-1} \frac{(t_{k}^{n})^{-\alpha}\varphi(t_{k}^{n}) - (t_{i}^{n})^{-\alpha}\varphi(t_{i}^{n})}{(t_{k}^{n} - t_{i}^{n})^{\alpha+1} 2^{n}} \right) \left( \widetilde{Y}_{t_{k+1}^{n}} - \widetilde{Y}_{t_{k}^{n}} \right)}{\sum_{k=0}^{2^{2n}-1} (t_{k}^{n})^{2\alpha} \left( \frac{\varphi(t_{k}^{n})}{(t_{k}^{n})^{2\alpha}} + \alpha \sum_{i=1}^{k-1} \frac{(t_{k}^{n})^{-\alpha}\varphi(t_{k}^{n}) - t_{i}^{-\alpha}\varphi(t_{i}^{n})}{(t_{k}^{n} - t_{i}^{n})^{\alpha+1}} \frac{1}{2^{n}} \right)^{2} \frac{1}{2^{n}}}{(9)}$$

where

$$\widetilde{Y}_{t_k} = \sum_{i=1}^{k-1} (t_i^n)^{-\alpha} (t_k^n - t_i^n)^{-\alpha} b^{-1} (t_i^n, X_{t_i^n}) \left( X_{t_{i+1}^n} - X_{t_i^n} \right).$$

In the general case formula (9) is not suitable for applications because it involves a lot of weakly singular kernels and it is quite impossible to get its convergence to the true value of the parameter. But even if we get the convergence, the simulation error will be so great that annihilate our efforts in discretization. In order to avoid this technical difficulties, we start with the simplest case. In order to avoid this technical difficulties, we start with the simplest case. Consider an equation

$$dX_t = \theta b(X_t) dt + b(X_t) dB_t^H.$$
(10)

In this case the maximum-likelihood estimator can be written as follows:

$$\hat{\theta}_t^{(1)} = \frac{\int_0^t s^{-\alpha} (t-s)^{-\alpha} b^{-1}(X_s) dX_s}{B(1-\alpha, 1-\alpha) t^{1-2\alpha}}.$$
(11)

Now we consider an estimator

$$\hat{\theta}_{n}^{(3)} = \frac{\sum_{k=1}^{2^{2n}-1} (t_{k}^{n})^{-\alpha} (2^{n}-t_{k}^{n})^{-\alpha} b^{-1} \left(X_{t_{k-1}^{n}}\right) \left(X_{t_{k}^{n}}-X_{t_{k-1}^{n}}\right)}{\mathrm{B}(1-\alpha,1-\alpha) 2^{n(1-2\alpha)}},$$

where  $t_k^n = \frac{k}{2^n}$ ,  $k = 0, 1, ..., 2^{2n}$ . This estimator is a discretized version of the estimator (11).

#### Theorem

Suppose that there exist positive constants  $C_1$ ,  $C_2$ ,  $C_3$ ,  $C_5$  and  $\rho \in (1/H - 1, 1]$ , such that (a)  $|b(x) - b(y)| \leq C_1 |x - y|$  for all  $x, y \in \mathbb{R}$ , (b)  $C_5 \leq |b(x)| \leq C_2(1 + |x|)$  for all  $x \in \mathbb{R}$ , (c)  $|b'(x) - b'(y)| \leq C_3 |x - y|^{\rho}$  for all  $x, y \in \mathbb{R}$ Then  $\hat{\theta}_n^{(3)} \xrightarrow{P_1} \theta$ ,  $n \to \infty$ . Moreover, for any  $\beta \in (1/2, H)$  and  $\gamma > 1/2$ there exists a random variable  $\eta = \eta_{\beta,\gamma}$  with all finite moments such that  $\left|\hat{\theta}_n^{(3)} - \theta\right| \leq \eta n^{\kappa + \gamma} 2^{-\tau n}$ , where  $\kappa = \gamma/\beta$ ,  $\tau = (1 - H) \land (2\beta - 1)$ .

- ・ 伺 ト ・ ヨ ト ・ ヨ ト ・ ヨ

## Introduction

### Model description

- Fractional Brownian motion
- Fractional derivatives
- Stochastic differential equation
- Assumptions

### 3 Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case a = b

### 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

### 5 Estimates for fractional derivatives of fBm and for solutions of SDE

Consider a stochastic differential equation

$$X_{t} = X_{0} + \theta \int_{0}^{t} a(X_{s}) ds + \int_{0}^{t} b(X_{s}) dB_{s}^{H}, \qquad (12)$$

where  $X_0$  is a non-random coefficient. In [Lyons (1998)], it is shown that this equation has a unique solution under the following assumptions: there exist constants  $\delta \in (1/H - 1, 1]$ , K > 0, L > 0 and for every N > 0 there exists  $R_N > 0$  such that

(A) 
$$|a(x)| + |b(x)| \le K$$
 for all  $x, y \in \mathbb{R}$ ,  
(B)  $|a(x) - a(y)| + |b(x) - b(y)| \le L |x - y|$  for all  $x, y \in \mathbb{R}$ ,  
(C)  $|b'(x) - b'(y)| \le R_N |x - y|^{\delta}$  for all  $x \in [-N, N], y \in [-N, N]$ .

イロト イポト イヨト イヨト 二日

Our main problem is the following: to construct an estimator for  $\theta$  based on discrete observations of X. Specifically, we will assume that for some  $n \ge 1$  we observe values  $X_{t_n^k}$  at the following uniform partition of  $[0, 2^n]$ :  $t_k^n = k2^{-n}$ ,  $k = 0, 1, \ldots, 2^{2n}$ . In order to construct consistent estimators for  $\theta$ , we need another technical assumption, in addition to conditions (A)–(C): (D) there exists a constant M > 0 such that for all  $x \in \mathbb{R}$ 

$$|a(x)| \ge M, \qquad |b(x)| \ge M.$$

(日) (同) (三) (三) (二)

We now define an estimator, which is a discretized version of a maximum likelihood estimator for F(X), where  $F(x) = \int_0^x b(y)^{-1} dy$ :

$$\hat{\theta}_{n}^{(4)} = \frac{\sum_{k=1}^{2^{2n}} (t_{k}^{n})^{-\alpha} (2^{n} - t_{k}^{n})^{-\alpha} b^{-1} \left(X_{t_{k-1}^{n}}\right) \left(X_{t_{k}^{n}} - X_{t_{k-1}^{n}}\right)}{\sum_{k=1}^{2^{2n}} (t_{k}^{n})^{-\alpha} (2^{n} - t_{k}^{n})^{-\alpha} b^{-1} \left(X_{t_{k-1}^{n}}\right) a \left(X_{t_{k-1}^{n}}\right) \frac{1}{2^{n}}},$$

where  $\alpha = H - \frac{1}{2}$ .

▲□▶ ▲□▶ ▲□▶ ▲□▶ □ のの⊙

We now define an estimator, which is a discretized version of a maximum likelihood estimator for F(X), where  $F(x) = \int_0^x b(y)^{-1} dy$ :

$$\hat{\theta}_{n}^{(4)} = \frac{\sum_{k=1}^{2^{2n}} (t_{k}^{n})^{-\alpha} (2^{n} - t_{k}^{n})^{-\alpha} b^{-1} \left(X_{t_{k-1}^{n}}\right) \left(X_{t_{k}^{n}} - X_{t_{k-1}^{n}}\right)}{\sum_{k=1}^{2^{2n}} (t_{k}^{n})^{-\alpha} (2^{n} - t_{k}^{n})^{-\alpha} b^{-1} \left(X_{t_{k-1}^{n}}\right) a \left(X_{t_{k-1}^{n}}\right) \frac{1}{2^{n}}},$$

where  $\alpha = H - \frac{1}{2}$ .

#### Theorem

With probability one,  $\hat{\theta}_n^{(4)} \to \theta$ ,  $n \to \infty$ . Moreover, for any  $\beta \in (1/2, H)$  and  $\gamma > 1/2$  there exists a random variable  $\eta = \eta_{\beta,\gamma}$  with all finite moments such that  $\left|\hat{\theta}_n^{(4)} - \theta\right| \leq \eta n^{\kappa+\gamma} 2^{-\tau n}$ , where  $\kappa = \gamma/\beta$ ,  $\tau = (1 - H) \land (2\beta - 1)$ .

・ 何 ト ・ ヨ ト ・ ヨ ト ・ ヨ

Consider a simpler estimator:

$$\hat{\theta}_{n}^{(5)} = \frac{\sum_{k=1}^{2^{2n}} b^{-1} \left( X_{t_{k-1}^{n}} \right) \left( X_{t_{k}^{n}} - X_{t_{k-1}^{n}} \right)}{\frac{1}{2^{n}} \sum_{k=1}^{2^{2n}} b^{-1} \left( X_{t_{k-1}^{n}} \right) a \left( X_{t_{k-1}^{n}} \right)}.$$

This is a discretized maximum likelihood estimator for  $\theta$  in equation (13), where  $B^H$  is replaced by Wiener process. Nevertheless, this estimator is consistent as well. Namely, we have the following result.

#### Theorem

With probability one,  $\hat{\theta}_n^{(5)} \to \theta$ ,  $n \to \infty$ . Moreover, for any  $\beta \in (1/2, H)$  and  $\gamma > 1/2$  there exists a random variable  $\eta = \eta_{\beta,\gamma}$  with all finite moments such that  $\left|\hat{\theta}_n^{(5)} - \theta\right| \leq \eta n^{\kappa+\gamma} 2^{-\tau n}$ , where  $\kappa = \gamma/\beta$ ,  $\tau = (1 - H) \land (2\beta - 1)$ .

白 医水理 医水黄 医水黄 医二黄

In the paper [Kozachenko et al (2015)] the following non-standard estimator for  $\theta$  in the equation (3) was considered:

$$\hat{\theta}_t^{(6)} = rac{\int_0^t a(s, X_s) b^{-2}(s, X_s) dX_s}{\int_0^t a^2(s, X_s) b^{-2}(s, X_s) ds}.$$

According to [Kozachenko et al (2015), Theorem 4], if the assumptions (I)–(IV), (VI)–(VII) hold and there exist such  $\beta > 1 - H$  and p > 1 that

$$\frac{T^{H+\beta-1}(\log T)^p \int_0^T \left| (D_{0+}^\beta \varphi)(s) \right| ds}{\int_0^T \varphi_s^2 ds} \to 0 \text{ a.s. as } T \to \infty$$

then the estimator  $\hat{\theta}_{T}^{(6)}$  is well-defined and strongly consistent as  $T \to \infty$ . We define a discretized version of  $\hat{\theta}_{\tau}^{(6)}$  for the equation

$$X_{t} = X_{0} + \theta \int_{0}^{t} a(X_{s}) ds + \int_{0}^{t} b(X_{s}) dB_{s}^{H}.$$
 (13)

Put

$$\hat{\theta}_{n}^{(7)} := \frac{\sum_{k=1}^{2^{2n}} a\left(X_{t_{k-1}^{n}}\right) b^{-2}\left(X_{t_{k-1}^{n}}\right) \left(X_{t_{k}^{n}} - X_{t_{k-1}^{n}}\right)}{\sum_{k=1}^{2^{2n}} a^{2}\left(X_{t_{k-1}^{n}}\right) b^{-2}\left(X_{t_{k-1}^{n}}\right) \frac{1}{2^{n}}}.$$

Put

$$\hat{\theta}_{n}^{(7)} := \frac{\sum_{k=1}^{2^{2n}} a\left(X_{t_{k-1}^{n}}\right) b^{-2}\left(X_{t_{k-1}^{n}}\right) \left(X_{t_{k}^{n}} - X_{t_{k-1}^{n}}\right)}{\sum_{k=1}^{2^{2n}} a^{2}\left(X_{t_{k-1}^{n}}\right) b^{-2}\left(X_{t_{k-1}^{n}}\right) \frac{1}{2^{n}}}.$$

Let

$$\widehat{\varphi}_n(t) := \sum_{k=0}^{2^{2n}-1} \varphi(t_k^n) I_{[t_k^n, t_{k+1}^n]}(t).$$

#### Theorem

Assume that there exist constants  $\beta > 1 - H$  and p > 1 such that

$$\frac{2^{n(H+\beta)}n^p\int_0^{2^n}\left|\left(D_{0+}^\beta\widehat{\varphi}_n\right)(s)\right|\,ds}{\sum_{k=1}^{2^{2n}}\varphi^2(t_{k-1}^n)}\to 0\quad \text{a. s. as }n\to\infty.$$

Then with probability one,  $\hat{\theta}_n^{(7)} \to \theta, n \to \infty$ .

A (1) > A (2) > A

### Example

Consider the following model:

$$dX_t = \theta b(X_t) dt + b(X_t) dB_t^H.$$

In this case the estimator  $\hat{\theta}_n^{(7)}$  has the form

$$\hat{\theta}_{n}^{(8)} = 2^{-n} \sum_{k=1}^{2^{2n}} b^{-1} \left( X_{t_{k-1}^{n}} \right) \left( X_{t_{k}^{n}} - X_{t_{k-1}^{n}} \right), \qquad (14)$$

$$\hat{\varphi}_{n}(t) = 1. \text{ Then } \left( D_{0+}^{\beta} \widehat{\varphi}_{n} \right)(s) = \frac{1}{\Gamma(1-\beta)} \cdot s^{-\beta} \text{ and}$$

$$\frac{2^{n(H+\beta)} n^{p} \int_{0}^{2^{n}} \left| \left( D_{0+}^{\beta} \widehat{\varphi}_{n} \right)(s) \right| ds}{\sum_{k=1}^{2^{2n}} \varphi^{2}(t_{k-1}^{n})} = \frac{n^{p}}{\Gamma(2-\beta) \cdot 2^{n(1-H)}} \to 0, \quad n \to \infty.$$

Consequently the estimator (14) is strongly consistent.

### Introduction

### Model description

- Fractional Brownian motion
- Fractional derivatives
- Stochastic differential equation
- Assumptions

### 3 Maximum-likelihood estimator

- The explicit form for the likelihood ratio
- A discretized version of MLE
- Estimation in the case a = b

### 4 Consistent estimators for drift parameter

- Assumptions
- Consistent Estimator 1
- Consistent Estimator 2
- Consistent Estimator 3

### 5 Estimates for fractional derivatives of fBm and for solutions of SDE

The proof of the strong consistency is based on the following estimate for the fractional derivative of  $B^{H}$ .

Let some  $\alpha \in (1 - H, 1/2)$  be fixed. Denote for  $t_1 < t_2$ 

$$Z(t_1, t_2) = \left( D_{t_2-}^{1-\alpha} B_{t_2-}^H \right) (t_1)$$
  
=  $\frac{e^{-i\pi\alpha}}{\Gamma(\alpha)} \left( \frac{B_{t_1}^H - B_{t_2}^H}{(t_2 - t_1)^{1-\alpha}} + (1-\alpha) \int_{t_1}^{t_2} \frac{B_{t_1}^H - B_{u}^H}{(u - t_1)^{2-\alpha}} du \right).$ 

イロト 不得下 イヨト イヨト

The following proposition is a generalization of [Kozachenko et al (2015), Theorem 3].

Theorem

For any  $\gamma > 1/2$ ,

$$\begin{aligned} \xi_{H,\alpha,\gamma} &:= \sup_{0 \le t_1 < t_2 \le t_1 + 1} \frac{|Z(t_1, t_2)|}{(t_2 - t_1)^{H + \alpha - 1} \left( |\log(t_2 - t_1)|^{1/2} + 1 \right) \left( \log(t_2 + 3) \right)^{\gamma}} \\ & (15) \end{aligned}$$
is finite almost surely.  
Moreover, there exists  $c_{H,\alpha,\gamma} > 0$  such that  $\mathsf{E}\left[ \exp\left\{ x \xi_{H,\alpha,\gamma}^2 \right\} \right] < \infty$  for  $x < c_{H,\alpha,\gamma}.$ 

イロト 不得下 イヨト イヨト

Fix some  $\beta \in (1/2, H)$ . Denote for  $t_1 < t_2$ 

$$\Lambda_eta(t_1,t_2)=1ee \sup_{t_1\leq u< v\leq t_2}rac{|Z(u,v)|}{(v-u)^{eta+lpha-1}}.$$

#### Theorem

There exists a constant  $M_{\alpha,\beta}$  depending on  $\alpha$ ,  $\beta$ , K, and L such that for any  $t_1 \ge 0, t_2 \in (t_1, t_1 + 1]$ 

$$|X_{t_2} - X_{t_1}| \leq M_{lpha,eta} \left( {\sf A}_eta(t_1,t_2)(t_2-t_1)^eta + {\sf A}_eta(t_1,t_2)^{1/eta}(t_2-t_1) 
ight).$$

### Corollary

For any  $\gamma > 1/2$ , there exist random variables  $\xi$  and  $\zeta$  such that for all  $t_1 \ge 0$ ,  $t_2 \in (t_1, t_1 + 1]$ 

$$|X_{t_2} - X_{t_1}| \leq \zeta (t_2 - t_1)^{eta} \left( \log(t_2 + 3) 
ight)^{\kappa}, \quad \Lambda_{eta}(t_1, t_2) \leq \xi (\log(t_2 + 3))^{\kappa eta},$$

where  $\kappa = \gamma/\beta$ . Moreover, there exists some c > 0 such that  $E\left[\exp\left\{x\xi^2\right\}\right] < \infty$  and  $E\left[\exp\left\{x\zeta^{2\beta}\right\}\right] < \infty$  for x < c. In particular, all moments of  $\xi$  and  $\zeta$  are finite.

#### Lemma

For any 
$$n \geq 1$$
 and any  $t_1, t_2 \in [0, 2^{2n}]$  such that  $t_1 < t_2 \leq t_1 + 1$ 

$$|X_{t_2}-X_{t_1}|\leq \zeta n^\kappa (t_2-t_1)^eta,\quad \Lambda_eta(t_1,t_2)\leq \xi n^\gamma.$$

In order to construct a consistent estimator, we need a lemma concerning discrete approximation of integrals.

Lemma

For all  $n \ge 1$  and  $k = 1, 2, ..., 2^{2n}$ 

$$\left|\int\limits_{t_{k-1}^n}^{t_k^n} \left(a(X_u) - a(X_{t_{k-1}^n})\right) du\right| \leq C\zeta n^{\kappa} 2^{-n(\beta+1)}$$

and

$$\left|\int\limits_{t_{k-1}^n}^{t_k^n} \left(b(X_u) - b(X_{t_{k-1}^n})\right) dB_u^{H,\theta}\right| \leq C\xi \zeta n^{\gamma+\kappa} 2^{-2n\beta}.$$

- Kozachenko Y., Melnikov A., Mishura Y. (2015). On drift parameter estimation in models with fractional Brownian motion. *Statistics*. Vol. **49**(1), pp. 35–62.
- Lyons T.J. (1998). Differential equations driven by rough signals. *Rev. Mat. Iberoamericana*. Vol. 14(2), pp. 215–310.
- Mishura Y.S. (2008). Stochastic calculus for fractional Brownian motion and related processes. Lecture Notes in Mathematics, vol. 1929. Springer-Verlag, Berlin.
- Y. Mishura and K. Ralchenko (2014). On drift parameter estimation in models with fractional Brownian motion by discrete observations. *Austrian Journal of Statistics*, **43**, 217–228.

< 回 ト < 三 ト < 三 ト

- Mishura Y., Ralchenko K., Seleznev O., Shevchenko G. (2014).
   Asymptotic properties of drift parameter estimator based on discrete observations of stochastic differential equation driven by fractional Brownian motion. *Modern Stochastics and Applications, Volume 90 of Springer Optimization and Its Applications,* 303–318
- D. Nualart and A. Rășcanu (2002). Differential equations driven by fractional Brownian motion. *Collectanea Mathematica*, **53**, 55–81.